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Mitigating analytical variability in fMRI with style transfer

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Abstract

We propose a novel approach to facilitate the re-use of neuroimaging results by converting statistic maps across different functional MRI pipelines. We make the assumption that pipelines used to compute fMRI statistic maps can be considered as a style component and we propose to use different generative models, among which, Generative Adversarial Networks (GAN) and Diffusion Models (DM) to harmonize statistic maps across different pipelines. We explore the performance of multiple GAN and DM frameworks for unsupervised multi-domain style transfer. We developed an auxiliary classifier that distinguishes statistic maps from different pipelines, allowing us to validate pipeline transfer, but also to extend traditional sampling techniques used in DM to improve the transition performance. Our experiments demonstrate that our proposed methods are successful: pipelines can indeed be transferred as a style component, providing an important source of data augmentation for future studies.

Keywords: style transfer, generative models, analytical variability, fMRI, data re-use

Introduction

Over the last decades, the question of understanding brain functions has taken an important place in many research fields. With the development of brain imaging techniques such as task-based functional MRI (task-fMRI), researchers can now explore the brain activity of individuals while they perform predefined tasks, and get a better understanding of the neural correlates of different cognitive processes.

However, the "reproducibility crisis" raised concerns about the reliability of published findings, including in neuroimaging (Button et al., 2013; Poldrack et al., 2017; Botvinik-Nezer and Wager, 2023), and prompted the adoption of new research practices. Efforts have been made to increase sample sizes by acquiring data from a larger number of participants for a few numbers of cognitive tasks (e.g. UK Biobank (Sudlow et al., 2015)) or for a small number of participants on a larger number of cognitive tasks (e.g. Individual Brain Charting (Pinho et al., 2018)). However, the number of research questions that can be explored is always limited by the characteristics of each dataset.

With the increased adoption of data sharing (Poline et al., 2012), more and more neuroimaging data are made available on dedicated platforms (e.g. OpenNeuro (Markiewicz et al., 2021) or NeuroVault (Gorgolewski et al., 2015)). Re-using shared data in new studies would allow researchers to explore new research questions, with larger and more diverse

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datasets, while bypassing the difficulties associated with acquiring new data. Derived data could also be combined instead of raw data through meta- and mega-analyses (Costafreda, 2009). This process also reduces privacy constraints and avoids costly re-computations.

In task-fMRI, due to the high flexibility of analytical pipelines (Carp, 2012), derived data shared on public databases often come from different pipelines. However, different pipelines can lead to different results (Botvinik-Nezer et al., 2020), and combining results from different pipelines in mega-analyses can lead to a higher risk of false positive findings (Rolland et al., 2022). To benefit from this large amount of derived data available, it is thus necessary to find a way to mitigate the effect of pipeline differences on derived data.

To mitigate the effect of different sources of variability, researchers usually perform data harmonization with techniques such as style transfer (Gatys et al., 2016) that allow learning mappings between different domains. This technique makes use of generative models such as Generative Adversarial Networks (GANs) (Goodfellow et al., 2014) and Diffusion Models (DMs) (Ho et al., 2020). Supervised frameworks (Isola et al., 2017; Saharia et al., 2022) can be trained to learn a mapping between data pairs from different domains. In contrast, unsupervised frameworks (Zhu et al., 2017; Sasaki et al., 2021; Liu et al., 2017) do not necessitate pairs of data in different domains for their training as they use constraints like cycle consistency (Zhu et al., 2017) or shared latent space assumption (Liu et al., 2017; Sasaki et al., 2021). These provide a good opportunity to benefit from large unlabeled databases and learn complex mapping without ground truth. By conditioning on domain-specific features, unsupervised frameworks also extend to multi-domain (Choi et al., 2018, 2021; Ho and Salimans, 2021) to learn transfer between multiple domains in a single model.

In this work, we explore the ability of style transfer frameworks to convert task-fMRI statistic maps between pipelines. Our goal is to propose a solution to mitigate the effect of pipeline differences for fMRI mega-analyses in order to benefit from the large amount of derived data shared on public databases. To be useful in real practice, the proposed method should rely on unpaired data and perform multi-domain transitions. To our knowledge, this application of style transfer to data conversion between different analysis pipelines is new, and off-the-shelf methods do not directly apply as these were not designed on the same type of data.

To tackle these challenges, we made the following contributions:

- We are the first to make the assumption that pipelines can be considered as a style property of statistic maps which can be transferred between maps.
- We re-implement three state-of-the-art style transfer frameworks based on GAN, namely Pix2Pix (Isola et al., 2017), CycleGAN (Zhu et al., 2017) and StarGAN (Choi et al., 2018), and adapt them to our 3-dimensional statistic maps.
- We re-implement a state-of-the-art conditional DM (Ho and Salimans, 2021) and adapt it for style transfer by conditioning the sampling on the source image.
- We explore different types of conditioning for DM frameworks: in particular using the latent space of an auxiliary classifier trained to distinguish statistic maps between pipelines, a task previously unexplored.

Materials and Methods

Dataset

We use group-level statistic maps from the *HCP multi-pipeline dataset*. More details can be found in (Germani et al., 2023). Briefly, this dataset is composed of subject-level (1,080 participants) and group-level (1,000 groups) statistic and contrast maps derived from raw data of the *Human Connectome Project Young Adult* S1200 release (Van Essen et al., 2013b). In this dataset, raw fMRI data for the motor task were analyzed with 24 different pipelines for the 5 contrasts: *right-hand*, *right-foot*, *left-hand*, *left-foot* and *tongue*. The pipelines used in this dataset vary in terms of software package, smoothing kernel Full-Width at Half-Maximum (FWHM), number of motion regressors, and derivatives of the Haemodynamic Response Function (HRF) included in the first-level analysis.

We explore in particular the statistic maps obtained with four different pipelines that differ in terms of software packages (SPM (Penny et al., 2011) or FSL (Jenkinson et al., 2012)) and the presence or absence of the derivatives of the HRF for the first-level analysis. We use all the available group-level statistic maps (N=1,000) for each pipeline for the contrast right-hand. In the following, these pipelines are labeled with "<software>-<derivatives>", for instance "fsl-1" means the use of FSL software package with HRF derivatives.

The selected group-level statistic maps are resampled to a size of $48 \times 56 \times 48$ and masked using the intersection mask of all groups. The voxel values are normalized between -1 and 1 for each statistic map using a min-max operation. The 1,000 groups are split into train and test with an 80/20 ratio and all models are trained and evaluated on the same sets. Further investigation about possible data leakage across groups is provided in Supplementary Figure 1 (Germani et al., 2024b).

GAN frameworks

First, we assess the potential of GAN frameworks to convert statistic maps between pipelines. In particular, we evaluate the performance of Pix2Pix (Isola et al., 2017), CycleGAN (Zhu et al., 2017) and StarGAN (Choi et al., 2018). A detailed description of each framework is available in the corresponding papers. We provide a quick description of the main properties of these models in Table 1.

Framework	Learning	Transition	Loss
Pix2Pix (Isola et al., 2017)	Supervised	One-to-one	Adversarial
			Reconstruction
CycleGAN (Zhu et al., 2017)	Unsupervised	One-to-one	Adversarial
			Cyclic
StarGAN (Choi et al., 2018)	Unsupervised	Multi-domain	Adversarial
			Cyclic
			Classification

Table 1: Description of GAN frameworks

Architecture and training We use the default architecture of these models, as described in their respective papers, and we only modify the 2-dimensional convolutions and batch

normalization layers to cope with our 3-dimensional statistic maps. These were implemented using PyTorch (Paszke et al., 2019) and each framework was trained for 200 epochs on 1 GPU NVIDIA Tesla V100.

DM frameworks

Due to the promising performance of DM on natural images and medical imaging (Dhariwal and Nichol, 2021), we also assess the potential of DM frameworks. However, only a few DM frameworks have been developed for style transfer, and to our knowledge, they rely on paired data (Saharia et al., 2022) or learn only one-to-one transitions (Pan et al., 2023). Thus, to perform multi-domain transitions, we adapt an existing conditional DM to style transfer tasks. We use the framework from (Ho and Salimans, 2021), which generates images conditioned using a one-hot encoding of the class (*i.e.* class vector). We extend this model to conditioning based on the latent space of an auxiliary classifier, inspired from (Preechakul et al., 2022). Both are unsupervised frameworks, learning multi-domain transitions. A more detailed description of the original framework is available in (Ho and Salimans, 2021).

Source content preservation To adapt our framework to style transfer, we first needed to find a solution to generate images that maintain the intrinsic properties of the source image. In (Saharia et al., 2022), authors concatenate the source image with random Gaussian noise to initialize the diffusion. Here, we propose to fix the initial state of the DM by directly using the forward diffusion process to generate a noisy version of the source image X_t . Then, the noisy source image is iteratively denoised using the predicted noise conditioned on the target domain and the reverse diffusion process.

Classifier conditioning We also extend the model from (Ho and Salimans, 2021) with conditioning on the latent space of an auxiliary classifier. In (Ho and Salimans, 2021), the diffusion is conditioned using a one-hot encoding of the domain, limiting the diversity of generated samples. In (Preechakul et al., 2022), a semantic encoder is used to guide sampling. We extend this idea by conditioning the model on a latent feature vector extracted from a pre-trained CNN. This CNN was pre-trained to distinguish pipelines from the statistic maps. The features are extracted just before the classification layer, to get a good representation to distinguish images across pipelines.

Multi-target images (Choi et al., 2021) showed that conditioning on multiple images generates images that share more coarse or fine features with the target ones depending on the number of selected images. Here, we aim to better represent the heterogeneity of the target domain. In practice, the whole set of images available in the target domain could be used. This is impractical for large datasets and might lead the model to focus on specific patterns of the target domain if these are over-represented in the dataset.

Architecture and training The neural network used to predict the noise follows a simple U-Net architecture (Ronneberger et al., 2015) with two downsampling and upsampling blocks with 3D convolution layers and skip connections. Hyperparameters are the following: t = 500 diffusion steps; linear noise schedule with variances in the range of $\beta_1 = 10^4$ and $\beta_t = 0.02$; batch size of 8 and learning rate of 1e-4. The model is implemented using PyTorch (Paszke et al., 2019) and trained for 200 epochs on 1 GPU NVIDIA Tesla V100.

The auxiliary classifier used to extract class conditional features contains five 3-dimensional convolution layers with 3-dimensional batch normalization and leaky rectified linear units (ReLU) activation functions, followed by a fully connected layer. The latent features correspond to 4,096 flattened vectors injected as conditioning to the U-Net. It is trained for 150 epochs using a learning rate of 1e-4 and a batch size of 64 on 1 GPU NVIDIA Tesla V100.

Evaluation metrics

We used two types of metrics: Pearson's correlation coefficient and Mean Squared Error (MSE) to study the adequacy of generated images to the ground truth target, and Inception Score (Salimans et al., 2016) (IS) to explore the quality and diversity of the generated images. IS combines the confidence of the class predictions (i.e. each image's label distribution p(Y|X)) with the variety in the output of the model (i.e. the marginal label distribution for the whole set of images P(Y)). As an additional evaluation criterion, we used the auxiliary classifier to classify the generated images and verify if these images were correctly classified in the target pipeline class.

Results

GAN frameworks

		$fsl-1 \rightarrow spm-0$	$spm-0 \rightarrow fsl-1$	$fsl-1 \rightarrow spm-1$	$fsl-1 \rightarrow fsl-0$
	IS		Mean correlation	ns (Std. errors)	
Initial	3.69	78.2 (0.5)	78.2 (0.5)	82.8 (0.3)	92.3 (0.5)
Pix2Pix	-	91.4 (0.1)	$89.1\ (0.2)$	90.1 (0.2)	$97.4\ (0.1)$
CycleGAN	-	85.5 (0.3)	$67.1\ (0.4)$	70.0 (0.5)	71.2(0.4)
StarGAN	3.63	90.5 (0.4)	86.8 (0.5)	87.6 (0.5)	91.5 (0.3)

	$fsl-1 \rightarrow spm-0$	$spm-0 \rightarrow fsl-1$	$fsl-1 \rightarrow spm-1$	$fsl-1 \rightarrow fsl-0$
		Mean MSE (Std. errors)	
Initial	0.0076 (0.0003)	0.0076 (0.0003)	0.0041 (0.0002)	0.0022 (0.0001)
Pix2Pix	$0.0027 \ (0.0001)$	$0.0014 \ (0.0001)$	$0.0025 \ (0.0001)$	$0.0005 \ (0.0)$
CycleGAN	$0.0049 \ (0.0002)$	0.0049 (0.0002)	$0.0072 \ (0.0002)$	0.0048 (0.0001)
StarGAN	$0.0035 \ (0.0002)$	0.002 (0.0001)	$0.0035 \ (0.0001)$	0.0017 (0.0001)

Table 2: Performance of GAN frameworks. IS means "Inception Score". Pearson's correlation (%) and Mean Squared Error (MSE) are computed between generated and ground truth images and averaged across 20 images. *Initial* represents the metrics between the source image (before transfer) and the ground-truth target image. Boldface marks the top model.

In Table 2, we show the performance of GAN frameworks for transfers between pipelines with: a different software and a different HRF (columns 1-4), a different software and the same HRF (columns 4-6) and, the same software and a different HRF (columns 6-8). Overall, using Pix2Pix (Isola et al., 2017) and StarGAN (Choi et al., 2018), the conversion of statistic maps between pipelines is successful, with increased correlations between target and generated maps compared to correlations between source and target (similar observations

are made with MSE, in Supplementary Tables), e.g. 91.4% for target-generated compared to 76.2% for source-target with Pix2Pix for conversion "fsl-1" to "spm-0".

We can point out the large superiority of the supervised Pix2Pix framework compared to unsupervised alternatives. By benefiting from paired data, Pix2Pix generates images closer to the target image than the source image for all transfers. Correlations between target and generated images are close to 0.9, which is nearly perfect. On the other hand, the Cycle-GAN (Zhu et al., 2017) framework gives surprising results, relatively low compared to other frameworks. While it makes use of a cyclic loss, similarly to StarGAN (Choi et al., 2018), it only learns transfers between two domains. We can suppose that StarGAN leverages the data from the multiple source domains and benefits from the additional classification loss, leading to higher performance in similar settings.

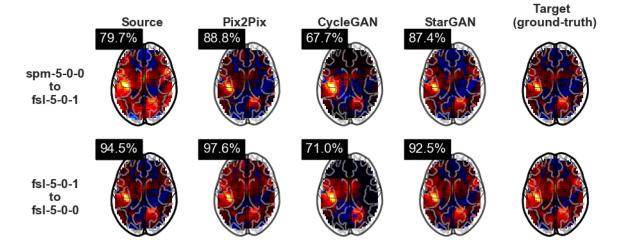


Figure 1: Generated images for two transfers and different competitors: Pix2Pix (Isola et al., 2017), CycleGAN (Zhu et al., 2017) and starGAN (Choi et al., 2018). Correlation with ground truth are indicated above each image (in percent).

In Figure 1, we illustrate two transfers: (first row) between pipelines with different software packages and different HRF (spm-0 to fsl-1) and (second row) between pipelines with the same software package and different HRF (fsl-1 to fsl-0). We randomly selected a statistic map of the source pipeline and generated the corresponding converted map in the target pipeline. We also display the ground-truth map in the target pipeline. Maps generated using Pix2Pix are closer to the ground truth, with more similar patterns, as seen with the similarity metrics.

DM frameworks

In Table 3, we show the performance of the DM frameworks for the same four transfers. Different frameworks are compared: one-hot conditioning from (Ho and Salimans, 2021), auxiliary classifier-conditioning with N=1 target image selected randomly, inspired from (Preechakul et al., 2022), and auxiliary classifier-conditioning with N=10 target images selected randomly (named $N=10,\infty$ in the Table).

		$fsl-1 \rightarrow spm-0$	$spm-0 \rightarrow fsl-1$	$fsl-1 \rightarrow spm-1$	$fsl-1 \rightarrow fsl-0$
	IS		Mean correlation	ns (Std. errors)	
Initial	3.69	78.2 (0.5)	78.2 (0.5)	82.8 (0.3)	92.3 (0.5)
One-hot	3.66	83.9 (0.7)	75.0 (0.9)	78.8 (0.8)	$81.1\ (0.6)$
N=1	3.70	85.4 (0.6)	77.4 (0.8)	80.1 (0.8)	82.8 (0.8)
$N=10, \infty$	3.86	86.1 (0.4)	78.9 (0.6)	81.5 (0.4)	84.1 (0.6)

	$fsl-1 \rightarrow spm-0$	$spm-0 \rightarrow fsl-1$	$fsl-1 \rightarrow spm-1$	$fsl-1 \rightarrow fsl-0$
		Mean MSE	(Std. errors)	
Initial	0.0076 (0.0003)	0.0076 (0.0003)	0.0041 (0.0002)	0.0022 (0.0001)
One-hot	0.0097 (0.0014)	$0.0048 \ (0.0007)$	0.0088 (0.0014)	$0.0043 \ (0.0003)$
N=1	$0.0053 \ (0.0003)$	$0.0037 \ (0.0003)$	$0.0073 \ (0.0009)$	$0.0037 \ (0.0003)$
N=10, ∞	$0.0043\ (0.0003)$	$0.0028 \ (0.0002)$	$0.0049\ (0.0003)$	$0.0029 \ (0.0002)$

Table 3: Performance of DM frameworks. IS means "Inception Score". Pearson's correlation (%) and Mean Squared Error (MSE) are computed between generated and ground truth images and averaged across 20 images per transfer. *Initial* represents the metrics between the source image (before transfer) and the target image. Boldface marks the top model.

The conversion between pipelines seems more difficult than with the GAN frameworks. While all models succeed in changing the class identified by a pipeline classifier to the target domain, the success of the conversion in terms of similarity to the ground truth is variable across transfers. For instance, all DM frameworks succeed for the transfer "fsl-1" to "spm-0", while none is successful for the transfer "fsl-1" to "fsl-0". These low performance could be explained by the difficulty of the models to learn differences between pipelines that provide similar results (*i.e.* whose results display very similar activation patterns).

Using a DM with auxiliary classifier conditioning and multiple target images $(N=10,\infty)$ improves the performance compared to the alternative frameworks. Both the quality and diversity of images are increased (IS=3.86). In terms of similarity to the ground truth, this framework also outperforms other DM models by up to 4% in correlations between ground-truth and generated image compared to (Ho and Salimans, 2021) for the transfer "spm-0" to "fsl-1" and up to 3% for "fsl-1" to "spm-0".

The first row of Figure 2 illustrates a transfer between pipelines with different software packages and different HRF ("spm-0" to "fsl-1"). The second row shows a transfer between pipelines with the same software package and different HRF ("fsl-1" to "fsl-0"). DM with multiple target images generates statistic maps close to the ground truth for both transfers, representing the intrinsic properties of the map while modifying its extrinsic properties to the target domain. Using the one-hot encoding, generated statistic maps seem far from the ground truth, failing to represent the full characteristics of the target domain.

The performance of DM frameworks remains notably inferior to the ones obtained with Pix2Pix (Isola et al., 2017) or StarGAN (Choi et al., 2018). This superiority can be explained by the differences between frameworks: GAN methods use adversarial training and StarGAN improves this by using a classifier loss and a cyclic-reconstruction loss. Moreover, the sampling process of GAN relies on the source image directly and does not require setting an initial state, which might facilitate the source content preservation. However,

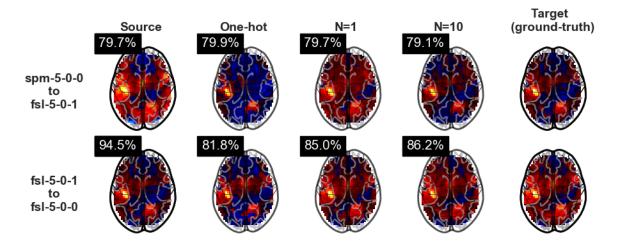


Figure 2: Generated images for two transfer and different competitors: conditioning with one-hot encoding (Ho and Salimans, 2021), with a classifier-conditioning N=1 and N=10 target images randomly selected. Correlations with ground truth are indicated above generated and source images (in percent).

we can note that Inception Scores (IS) obtained with DM frameworks are better than the ones obtained with StarGAN, which indicates that images generated by DM frameworks are more diverse. This observation is consistent with the literature (Dhariwal and Nichol, 2021) and the sampling process of DM frameworks which includes randomness.

Conclusion

In this study, we explored the potential of style transfer frameworks on the task of converting fMRI statistic maps between different pipelines. We showed that the StarGAN framework, trained on unsupervised and multi-domain data, could be easily trained and applied to generate statistic maps that maintain the intrinsic properties of brain activity while changing the style of the image. These newly generated data could be used to build valid mega-analyses on heterogeneous datasets and hence increase sample sizes in fMRI data analysis. Future works will focus on validating these assumptions by evaluating the false positives and false negatives rates of mega-analyses built with converted statistic maps.

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Data statement

This study was performed using derived data from the HCP Young Adult (Van Essen et al., 2013b), publicly available at ConnectomeDB. Data usage requires registration and agreement to the HCP Young Adult Open Access Data Use Terms available at: (Van Essen et al., 2013a).

The HCP multi-pipeline dataset (Germani et al., 2023) is publicly available on Public-nEUro (at Rigshopitalet, 2023): https://publicneuro-catalogue.netlify.app/dataset/PN000003%20HCP%20multipipelines/V1.

Ethics

This study was performed using derived data from the HCP Young Adult (Van Essen et al., 2013b). No experimental activity involving the human participants was made by the authors. Only shared data were used.

Written informed consent was obtained from participants and the original study was approved by the Washington University Institutional Review Board.

We agreed to the HCP Young Adult Open Access Data Use Terms available at: (Van Essen et al., 2013a).

Code and data availability

All the scripts used to perform the study (models training, testing and performance evaluation) are available on Software Heritage: swh:1:snp:b0b52aa88bef8f4411bdd7e00a2d71715d7830bb (Germani et al., 2024a).

Derived data such as pre-trained models and computed metrics are available on Zenodo (Germani et al., 2024b).

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Supplementary materials

Generalizability study

Ideally, researchers should be able to re-use a model trained to convert statistic maps of a task for another one. Thus, we test the generalizability of the frameworks trained to convert statistic maps from a particular task to statistic maps of other tasks. Here, we explore the generalizability of StarGAN trained on maps of right-hand to maps of right-foot and left-hand.

	$fsl-1 \rightarrow spm-0$	$spm-0 \rightarrow fsl-1$	$fsl-1 \rightarrow spm-1$	$fsl-1 \rightarrow fsl-0$			
Converting right-foot statistic maps with:							
Initial 86.2 86.3 85.8 95.9							
Trained on $right$ -foot	90.5	88.8	88.9	93.1			
Trained on right-hand	71.2	71.0	63.0	82.2			
Converting left-hand statistic maps with:							
Initial	82.3	82.3	85.9	92.9			
Trained on left-hand	88.4	85.4	86.8	85.8			
Trained on right-hand	73.2	74.5	69.5	75.2			

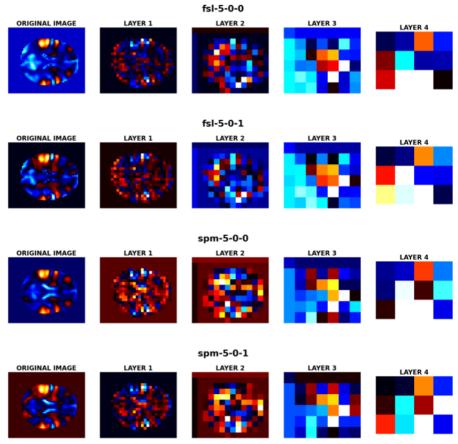
Supplementary Table 1 - Robustness to distribution shifts (i.e. trained and evaluated with statistic maps from different tasks) of StarGAN. Pearson's correlation (%) is computed between generated and ground truth and averaged across 20 images per transfer. Initial represents the metrics between the source image (before transfer) and the target image.

Supplementary Table 1 shows the performance of the StarGAN framework trained on right-hand statistic maps when applying it to statistic maps of right-foot and left-hand. We also show the performance of StarGAN trained directly on right-foot and left-hand for comparison. Our results show that the StarGAN framework does not behave positively when applied to a task different from the task used in the training data: the generated images seem further from the target images (e.g. 71.2% for the first transfer between "fsl-1" to "spm-0") than the source image was from the target (e.g. 86.2% in this case). We can see a large performance drop between the framework trained on statistic maps from the task compared to the one trained on maps from another task. Similar observations can be made for generalizability to closer tasks (here, frameworks trained on right-hand evaluated on left-hand). These results make us suppose that the mapping from one pipeline to another is different between tasks and thus, if the same model can be used for different subjects on the same task, different models should be trained to transfer statistic maps from tasks unseen during training.

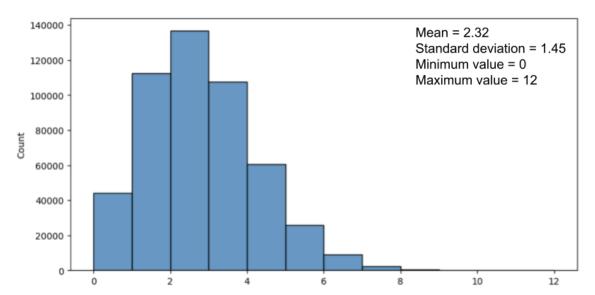
Supplementary figures

Pipelines	Layer 1	Layer 2	Layer 3	Layer 4		
Same software, different parameters						
fsl-5-0-0 / fsl-5-0-1 86.5 91.4 95.4 99.2						
spm-5-0-0 / spm-5-0-1	86.5	90.9	94.2	98.4		
Same parameters, different software						
fsl-5-0-0 spm-5-0-0	88.8	88.2	93.6	98.2		
fsl-5-0-1 spm-5-0-1	84.8	85.8	92.4	98.0		
Different software, different parameters						
fsl-5-0-0 spm-5-0-1	74.5	81.0	88.7	97.1		
fsl-5-0-1 spm-5-0-0	74.8	77.7	88.2	97.3		

Supplementary Table S1. Mean correlations between feature maps learned at each layer for each pair of pipelines. Features are close for pipelines sharing the same software at Layer 4, which might explain the difficulty to rely on these features to perform transfer.



Supplementary figure S1. Original mean statistic maps (column 1) and mean feature maps across groups learned by the pipeline classifier for the first 4 convolutional layers for the different classes. Pipelines with the same software show similar feature maps at Layer 2 and 3.



Supplementary Figure S2. Histogram of the number of shared participants between two groups for each pair of groups across the whole dataset. While shared participants between groups can impact our results by slightly over-estimating our performance, the impact is likely to be low due to the small number of shared participants (2.3 on average). In addition, this has no impact the conclusions of our study on the comparison of performance between different models as all models are trained and evaluated on the same sets of groups.